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1                   **Relating Subjective Ride Quality Ratings to Objective Measures**

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3                   **Raj Bridgelall**, Ph.D., Corresponding Author

4                   Associate Professor, Department of Transportation, Logistics & Finance

5                   College of Business, North Dakota State University

6                   Fargo, ND 58108; Email: raj@bridgelall.com, ORCID: 0000-0003-3743-6652

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9                   **Abstract**

10 Agencies have long used subjective roughness ratings from panels of users to inform policy  
11 development on road maintenance strategies. The commoditization of electronics motivated the  
12 development of more objective, automated, and cost-effective measurement technologies.  
13 Consequently, there has been an explosion of ensemble measurements using smartphones or  
14 connected vehicles. Nevertheless, agencies have no means of relating those sensor-based  
15 measurements to their customary linguistic scale of human perceived roughness levels. This  
16 research relates subjective ratings of roughness from regular passengers of public bus transit to  
17 simultaneous smartphone-based objective measures of roughness. The findings are that regular  
18 bus riders consistently distinguished between the extreme values of measured roughness but not  
19 the intermediate values. Ratings are also less distinguishable for smoother rides than for rougher  
20 rides. The experiments also reveal a phenomenon of *roughness acclimation* that leads to biased  
21 ratings from regular users of a road segment.

22  
23 **Keywords:** bus ride quality; connected vehicles; panel ratings; road profilers; road roughness

24 Declaration of Interest: None

25

## 26 **1 Introduction**

27 Transportation agencies use ride quality ratings to inform policy development on road network  
28 maintenance from resurfacing to replacement. Prior to the introduction of objective measures  
29 such as the international roughness index (IRI), agencies used panel ratings of ride quality based  
30 on the subjective opinions of users deemed to be experts (Gillespie, Sayers, & Queiroz, 1986).  
31 For instance, agencies used a present serviceability index (PSI) to represent a present  
32 serviceability rating (PSR) based on the ride comfort experienced across pavements of varying  
33 condition. However, with the introduction of technologies to measure pavement roughness,  
34 agencies began to transition away from expert panels to reduce expenses and inconsistencies.  
35 Manufacturers progressively introduced new equipment to improve the consistency of IRI data  
36 but even so, the reporting methods were inconsistent among agencies (Múčka, 2017).  
37 Consequently, agencies began to develop mathematical relationships to predict their familiar  
38 linguistic categories of perceived roughness from the IRI measurements. Even so, the  
39 considerable extent of the road network and high traffic volumes hindered practical IRI  
40 assessments. Also, agencies could not afford to more frequently monitor pavement roughness  
41 because of the relatively prohibitive cost of specialized vehicles such as inertial profilers.

42 To find more affordable solutions, researchers recently began to investigate the viability  
43 of combining measurements from smartphones or connected vehicles (Bridgell, et al., 2020).  
44 However, such approaches can produce large measurement variations because of differences in  
45 device sensitivity, orientation, and placement (Medina, Salim, Underwood, & Kaloush, 2020).  
46 Future connected vehicles offer the potential to reduce such measurement variations by adopting  
47 standards and methods of calibration. In anticipation of achieving standardized objective

48 roughness measures from future connected vehicles, agencies will still need to know how those  
49 measures relate to roughness levels perceived by human riders.

50 The **goal** of this research, therefore, is to relate a recently proposed objective  
51 measurement of ride quality using smartphones to subjective ratings from the traveling public.  
52 The experiments used five different bus route segments to evaluate the extent that the traveling  
53 public could perceive objective differences in the ride quality. The experiments associated the  
54 roughness measured for each trip with responses from a corresponding ride quality survey. Bus  
55 riders rated their perceived ride quality within one of five linguistic categories ranging from  
56 “very smooth” to “very rough.” Hence, the **contributions** of this research are:

- 57 1) A direct comparison of how subjective ride quality ratings from public transit users  
58 correspond to the objective values of ride roughness measured.
- 59 2) Show how trends in the association of measured and perceived roughness levels  
60 uncovered the phenomenon of roughness acclimation.

61 The organization of the remainder of this paper is as follows: Section 2 reviews the literature on  
62 ride quality assessments and evolution. Section 3 discusses the method used to objectively  
63 measure ride quality using a smartphone, the data collection setup, and the ride quality survey.  
64 Section 4 displays the results through a series of statistical charts and tests. Section 5 discusses  
65 the implications of the results and the main findings. Section 6 concludes the study, offers  
66 considerations for replicating the work, and hints at future work.

## 67 **2 Literature Review**

68 Early methods of ride quality assessment surveyed panels of experts to report roughness levels  
69 on a subjective rating scale (Faris, BenLahcene, & Hasbullah, 2012). However, an early  
70 investigation of ride quality rating scales found that there was widespread disagreement on

71 comfort criteria based on g-forces and vibration frequency (Dempsey, Coates, & Leatherwood,  
72 1977).

73 To improve the consistency of rating ride quality, Nick and Janoff (1983) were among  
74 the first to develop models to predict subjective ratings from objective measurements of profile  
75 roughness (Nick & Janoff, 1983). They found that with careful instructions, the mean subjective  
76 ratings were directly proportional to the mean measurements of roughness using a Mays ride  
77 meter. The  $R^2$  of their regression models were greater than 0.91. Their finding also highlighted  
78 that, to achieve high accuracy and consistency, the development of useful regression models  
79 requires the use of expert raters. With this understanding, Janoff (1986) later introduced a “ride  
80 number,” which related objective measurements of a physical profile roughness to a subjective  
81 rating scale of repair needs. However, the method limited assessments to pavement profile  
82 frequencies between 0.125 and 0.630 cycles per foot (Janoff, 1986). As new methods of physical  
83 profile measurements evolved, transportation agencies began to update their regression models.  
84 For example, in 1986, the Texas Department of Transportation (DOT) regressed panel ratings on  
85 measures of the root-mean-square of vertical acceleration (RMSVA) to update its present  
86 serviceability index for pavements (Nair & Hudson, 1986). In addition to roughness  
87 measurements, some condition indices also incorporate measurements of structural factors and  
88 transversal unevenness (Ruotoistenmäki & Seppälä, 2007).

89 The need for a global standard of ride quality assessment emerged, which resulted in the  
90 International Roughness Index (IRI). The IRI emerged as the most widespread measure of ride  
91 roughness; it measures the accumulation of absolute vertical profile displacement (Gillespie,  
92 Sayers, & Queiroz, 1986). Even so, agencies around the world specify the IRI differently  
93 (Múčka, 2017). In fact, Liu et al. (1999) found that subjective ratings based on the ride number

94 did not correlate well with the IRI based on a regression  $R^2$  of only 0.62 (Liu, Gazis, & Kennedy,  
95 1999). Their explanation was that humans are more sensitive to “jerk” motions due to changes in  
96 vertical accelerations rather than accumulated vertical displacements. In agreement, Yu et al.  
97 (2006) later found that jerk, which is speed sensitive, can be a better predictor of subjective  
98 roughness ratings (Yu, Chou, & Yau, 2006). With the development of many different scales of  
99 perceived ride comfort, Loprencipe et al. (2017) found that they could lead to different ride  
100 quality assessments for the same pavement (Loprencipe & Zoccali, 2017).

101         Although it is not the focus of this research to study the various sources of ride roughness  
102 and how they relate to pavement condition, it is helpful for readers to understand that variations  
103 in vehicle speed, suspension system design, route geometry, and driving behavior such as abrupt  
104 accelerations, braking, and sharp turning can produce varying degrees of ride roughness even  
105 when traversing the same pavement segment (Loprencipe, Zoccali, & Cantisani, 2019). For  
106 example, Wählberg (2006) found that driver training to operate buses for greater fuel efficiency  
107 also resulted in more comfortable passenger rides (Wählberg, 2006). Maternini & Cadei (2014)  
108 found that the increased accelerations from traversing roundabouts also reduced the levels of ride  
109 comfort (Maternini & Cadei, 2014). In related works, Zhao et al. (2016) applied the ISO 2631  
110 standard to measure bus ride comfort using smartphones, but the results were not consistent  
111 without signal filtering and spatial transformation (Zhao, Guo, & Zeng, 2016). Barabino et al.  
112 (2019) developed a new scale to evaluate bus driving style by using the ISO 2631 standard  
113 (Barabino, Coni, Olivo, Pungillo, & Rassa, 2019).

114         More recently, new methods to objectively measure ride quality with smartphones and  
115 crowdsourcing has emerged (Medina, Salim, Underwood, & Kaloush, 2020). Loprencipe et al.  
116 (2021) found that inertial measurements correlated well with typical pavement roughness indices

117 (Loprencipe, de Almeida Filho, de Oliveira, & Bruno, 2021). Such methods extend beyond road  
118 pavements to include railways (Rodríguez, Sañudo, Miranda, Gómez, & Benavente, 2021).  
119 Recently, Bridgelall (2022) introduced a composite roughness index (CRI) to characterize  
120 roughness from multidimensional movements along any path, including linear and rotational  
121 motions (Bridgelall, 2022). This work accessed and used the data from the Bridgelall (2022)  
122 experiments.

123         Despite the proliferation of studies that use smartphones to collect roughness data, there  
124 are some important limitations. For example, different smartphone brands and models produce  
125 different results because of variations in the sensitivity of their embedded sensors. Hence, Yang  
126 et al. (2020) discussed methods to calibrate smartphones for more consistent measures of  
127 roughness (Yang, Hu, Ahmed, Bridgelall, & Huang, 2020). Crowdsourcing will also produce  
128 large variations in measurements because of the wide variety of smartphone brands and models  
129 used, differences in their accelerometer sample rate, and the uncontrollability of their placement  
130 and orientation in vehicles.

### 131 **3 Methodology**

132 The methodology was a two-step process. It involved using the same smartphone to collect  
133 objective roughness data while surveying individual bus riders to rate the roughness of each bus  
134 ride. The next three subsections describe the roughness index used, the data collection, and the  
135 linguistic categories used to characterize the level of roughness experienced.

#### 136 **3.1 Roughness Index**

137 The measurements used the CRI introduced by Bridgelall (2022) because it is the only index that  
138 accounts for roughness produced by the three linear and three angular dimensions of motion  
139 (Bridgelall, 2022). Accelerations along the linear dimensions produce roughness in the lateral,

140 longitudinal, and vertical directions whereas accelerations in the angular dimensions can produce  
 141 discomfort such as head tossing, swaying, or other rotational motions.

142 The measure uses a RIF-transform to compress g-force units per meter of travel distance  
 143 for each of the six roughness components. The formula is

$$R_g^L = \sqrt{\frac{1}{L} \sum_{n=0}^{N-1} |g_n v_n|^2 \Delta t_n} \quad (1)$$

144 where  $g_n$  is the g-force sampled by the embedded smartphone inertial sensor.  $v_n$  is the vehicle  
 145 speed sampled by the embedded smartphone speed sensor.  $\Delta t_n$  is the time interval between  
 146 recording samples of those sensor signals.  $L$  is the traversal distance window size for  
 147 compressing the measured signals with a RIF Transform to produce an average g-force  
 148 experienced (in one of the six roughness dimensions) per unit of travel distance  $L$ .  $N$  is the  
 149 number of signal samples taken within each distance window and  $n$  is the sample index. Per the  
 150 Bridgelall reference, the interpretation of RIF-index  $R_g^L$  is the average g-force experienced in one  
 151 of the six roughness dimensions specified after traveling a distance  $L$  along the traversal path. As  
 152 described by Bridgelall (2022), the composite measure is the resultant roughness  $R_T^L$  experienced  
 153 as

$$R_T^L = \sqrt{(R_x^L)^2 + (R_y^L)^2 + (R_z^L)^2 + \left( (R_w^L)^2 + (R_p^L)^2 + (R_r^L)^2 \right)^2} \quad (2)$$

154 where  $R_x^L$ ,  $R_y^L$  and  $R_z^L$  are the RIF-indices of roughness in the lateral, longitudinal and vertical  
 155 directions, respectively. Similarly,  $R_w^L$ ,  $R_p^L$ , and  $R_r^L$  are the RIF-indices of roughness due to  
 156 changes in yaw, pitch, and roll, respectively.

### 157 **3.2 Roughness Data Collection**

158 Bridgelall (2022) simultaneously collected CRI measurement data and ride quality survey

159 responses from bus passengers. For consistency, the same smartphone (iPhone® 6S) collected  
160 the data to produce the CRI values for all bus rides. The smartphone used a free app called  
161 PAVVET that provided data files with samples of the variables  $g_n$ ,  $v_n$ , and  $\Delta t_n$  for computation of  
162 the RIF indices offline (Yang, Hu, Ahmed, Bridgelall, & Huang, 2020). The setup was identical  
163 on each bus; sticky tape secured the smartphone flat onto the center seat. That is, an identical  
164 setup that used both the same smartphone and app assured data consistency. There were at least  
165 30 data collection sessions per route segment, which amounted to a total of 164 data collection  
166 sessions across all route segments. A total of 18 different buses traversed the five different route  
167 segments. The setting was Fargo, North Dakota in the United States. The labels for the routes  
168 were EM (from Essentia Hospital to the Mall), SG (from Sanford Hospital to the Ground  
169 Transportation Center), UG (from University Drive to the Ground Transportation Center), MW  
170 (from the Mall to Walmart), and WM (from Walmart to the Mall). Bridgelall (2022) provides  
171 further details of the data collection, setup, and route map in his paper describing the nature of  
172 the CRI (Bridgelall, 2022), so this paper does not repeat those.

### 173 **3.3 Roughness Surveys**

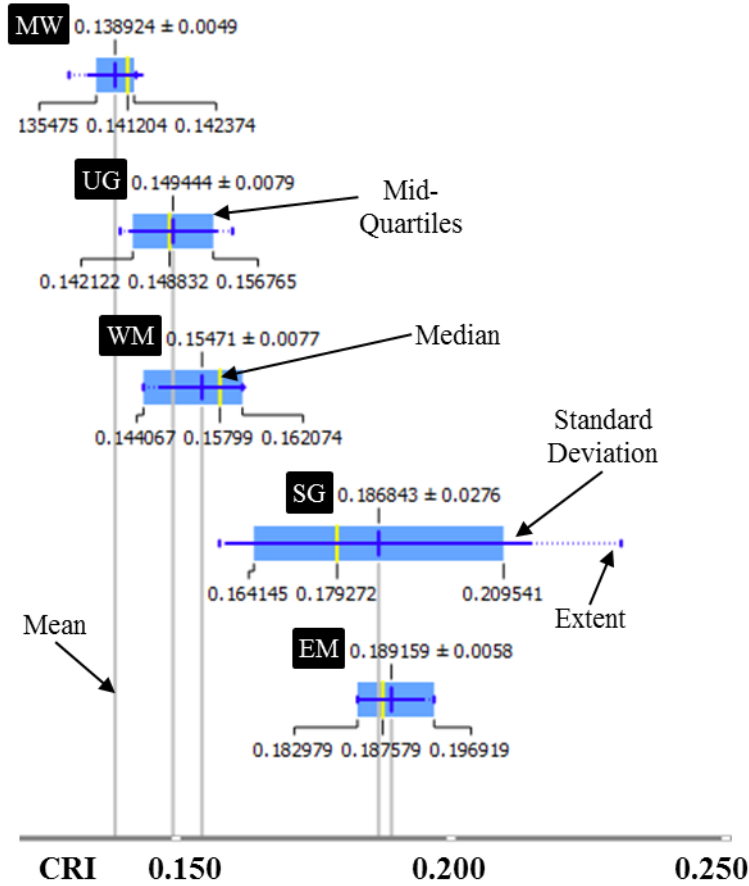
174 At the end of each trip, research personnel handed out a simple survey that asked respondents to  
175 rate the roughness of the bus ride into one of five linguistic categories: 1: “very smooth,” 2:  
176 “smooth,” 3: “neutral,” 4: “rough,” and 5: “very rough” without providing any further  
177 instructions. Hence, the survey reflected the subjective opinions of regular bus riders rather than  
178 those of ride quality experts. Road unevenness, bus operator controls, and variations in the  
179 suspension system performance were the main sources of roughness variations within and across  
180 route segments. Therefore, every bus ride produced a different level of roughness that the riders  
181 rated subjectively, and the device simultaneously measured objectively.



## 182 **4 Results and Discussions**

183 There were 334 survey respondents across all route segments. Figure 1 is a box plot that  
184 summarizes statistics of the CRI measurement from each of the five route segments. The box  
185 plot shows several statistics simultaneously—the mean (blue vertical line with gray vertical line  
186 extended to the horizontal axis), median (yellow vertical line), standard deviation (blue  
187 horizontal solid line), mid-quartiles (blue box from the 25th percentile to the 75th percentile),  
188 and data extent from the minimum to the maximum values (blue horizontal dotted line), as  
189 labeled. It is evident that the distributions of the measured CRIs for each route segment  
190 overlapped. For example, there were large overlaps in the standard deviations of the CRI  
191 distributions from route segments UG and WM, and SG and EM. However, a statistical test  
192 revealed that the mean roughness across each route segment was different. With an analysis of  
193 variance (ANOVA) F-statistic of 6.703 and a p-value of 0.004, the statistical test rejected the null  
194 hypothesis that the distribution means were the same. That is, the mean CRI for each route was  
195 significantly different in a statistical sense, which meant that the objective ride quality was also  
196 different.

197 Figure 2a shows the rating category distribution of the survey responses for each route  
198 segment. Figure 2b shows the corresponding proportion of all respondents for the rating  
199 categories in each route segment.



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Figure 1: Box plot of CRI measurements for each route.

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There was a mix of roughness levels perceived for each route, but their distributions were different. Most respondents rated their ride as “smooth” across all route segments. The proportion of respondents rating the ride as “rough” increased in correspondence with the mean CRI value for each segment. Conversely, the proportion of respondents rating their ride as “very smooth” decreased with increasing mean CRI value for each segment. No one rated a ride as “very rough” for any of the segments.

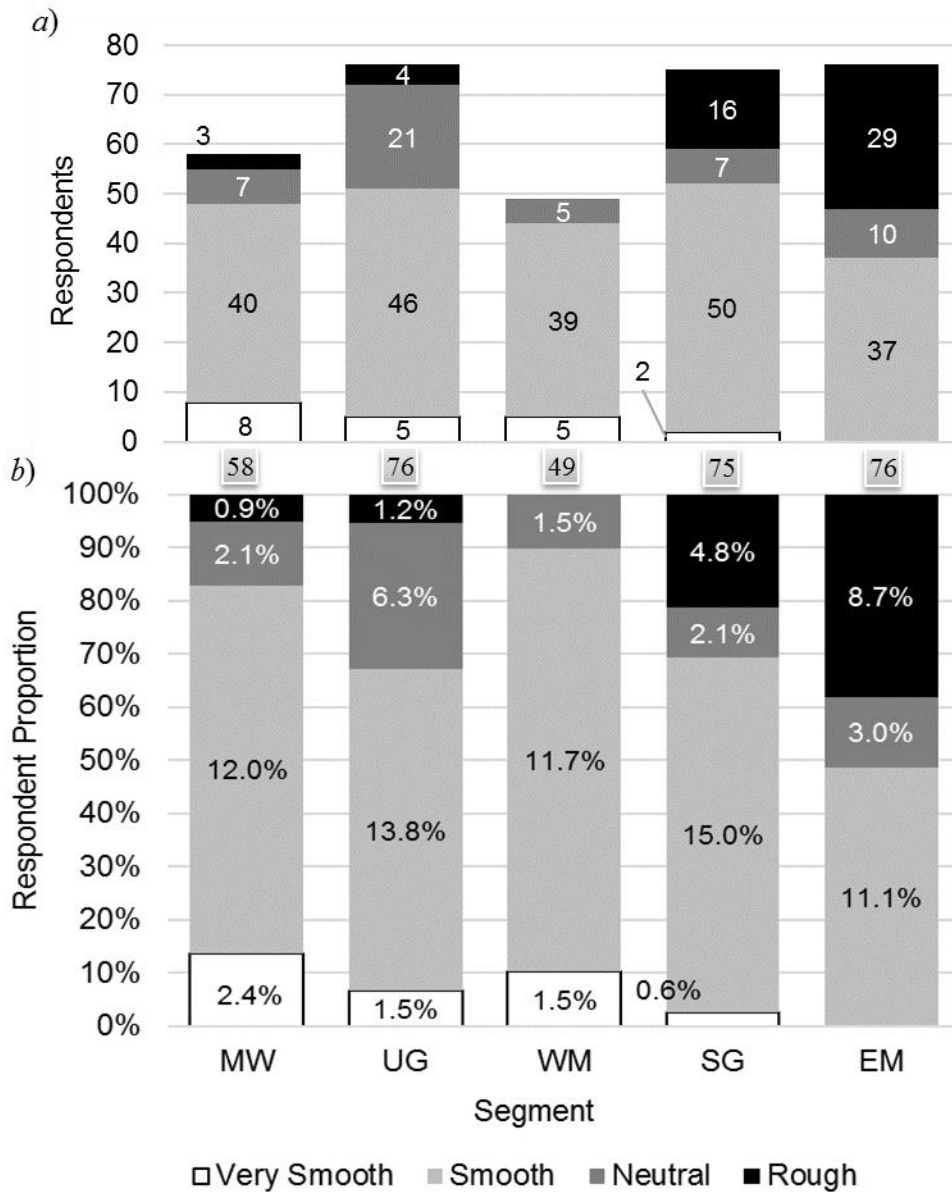


Figure 2: a) Number and b) proportion of respondents by segment and rating category.

Figure 3 is a box plot of the CRI measurements associated with each of the rating categories across all segments. Table 1 summarizes the results of the associated ANOVA or t-tests, which rejected the hypothesis that the CRI means are indistinguishable, except for the case between “smooth” and “neutral” ratings where the p-value is much greater than 0.05.

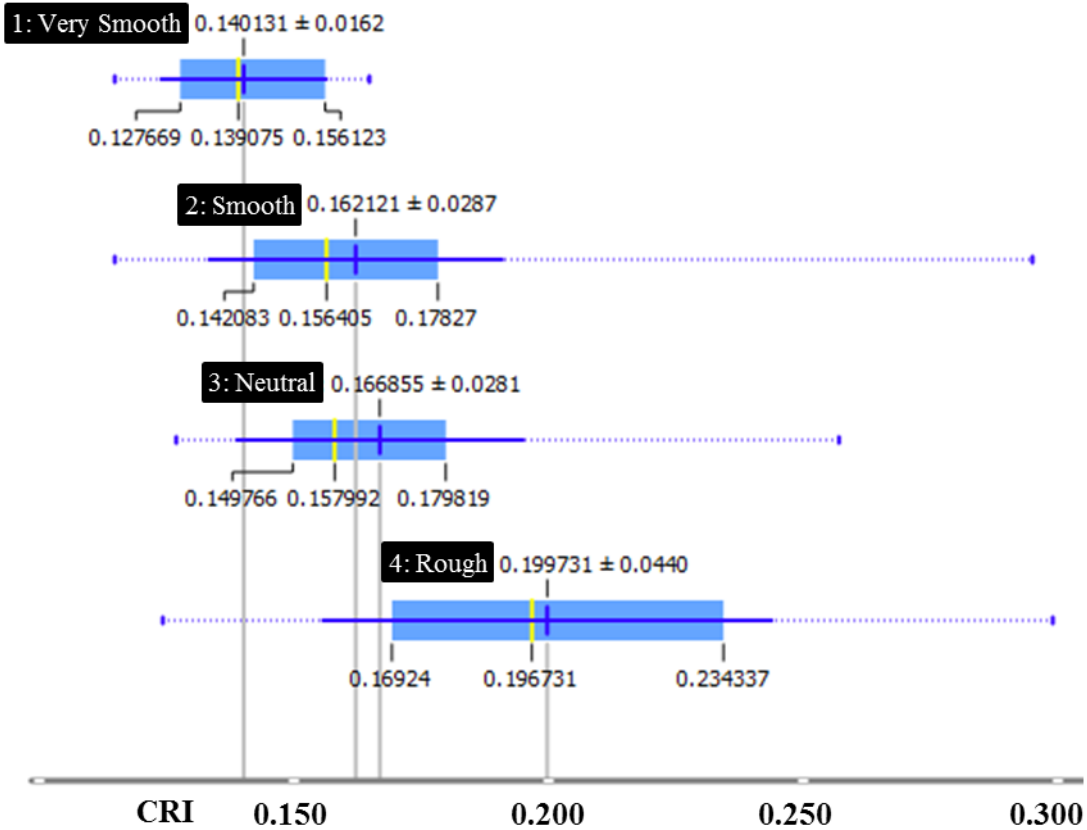


Figure 3: Box plot of CRI measurements associated with each category of roughness rating.

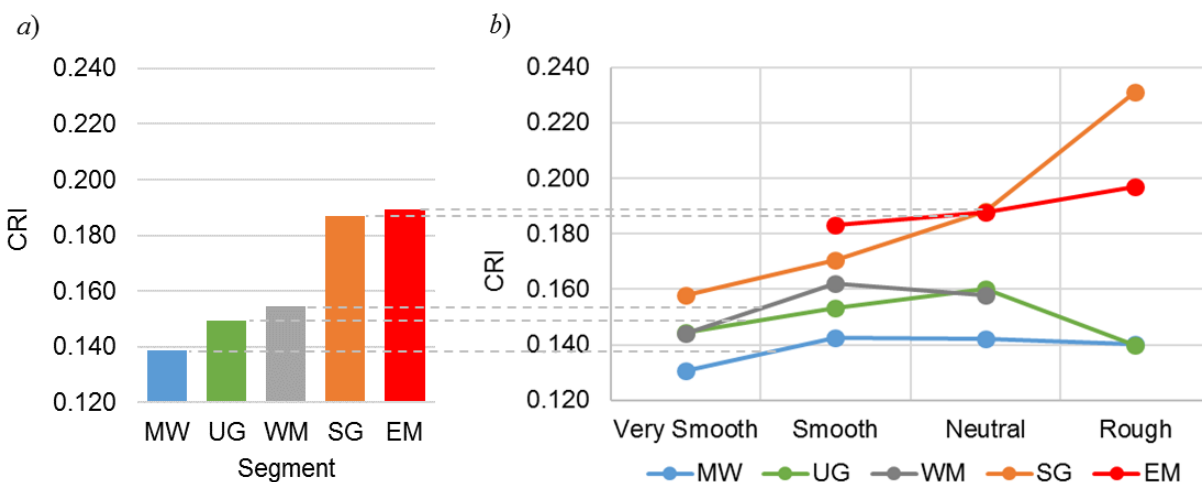
Table 1. Statistical Tests for Distinguishability of Distribution Means

ANOVA or T-Test	F-Statistic	p-value	H0: Series means are indistinguishable
Distributions 1, 2, 3, 4	25.776	0.000	Reject
Distributions 2, 3	1.067	0.289	Cannot reject
Distributions 1, 2, 4	37.532	0.000	Reject
Distributions 1, 3, 4	24.198	0.000	Reject

This result suggested that in general, riders associated both “smooth” and “neutral” ratings with nearly the same range of measured CRI values. There is a distinct separation of CRI distributions between the “very smooth” and “rough” ratings. The mean CRI value for the combined “smooth” and “neutral” distributions of 0.165 is a suitable threshold that clearly distinguishes between “very smooth” and “rough” ratings. Hence, agencies can conduct similar experiments with their own unique sensor setup and vehicle to produce similar statistics that

226 reveal a distinguishing CRI threshold above which their particular application of ride quality  
227 assessment may warrant further scrutiny.

228 Figure 4a plots the average CRI measured for each route segment and Figure 4b plots the  
229 average CRI associated with each rating category of ride quality. For the two roughness routes of  
230 EM and SG, the trend is monotonically increasing mean CRI values with categories of increasing  
231 roughness perception. The trend is not as consistent for the smoother routes of MW, UG, and  
232 WM. For the MW and WM segments, there was no significant difference in the average CRI  
233 values associated with the “smooth” and “neutral” categories. The trends were nearly the same  
234 for the smoother UG and WM segments. This suggests that the perception of roughness  
235 differences for the lower CRI values measured might be less discernable.



236  
237 Figure 4: Average CRI a) by route segment and b) average CRI associated with each rating of ride quality.

238 There was an anomaly for the MW and UG segments where the average CRI associated  
239 with the “rough” rating was lower than those of all the other rating categories. However, this  
240 result was likely due to an extreme rating by a small minority because only seven riders (Figure  
241 2a) rated those two segments in the “rough” category. There were no ratings for “very smooth”  
242 on the EM segment, which was the roughest segment based on the objective CRI measurements.

243 There were also no ratings for “rough” on the WM segment, which was approximately 23% less  
244 rough than the roughest route segment based on the average CRI value measured.

245 Across all route segments, riders clearly distinguished between the extreme values of  
246 measured roughness with ratings of “very smooth” and “rough” rides. However, riders associated  
247 the intermediate values of measured roughness as either “smooth” or “neutral” without a  
248 statistically clear distinction between their mean values. These results suggest that the traveling  
249 public can more consistently perceive differences in ride quality when the overall ride is rougher  
250 than when it is smoother. This result parallels the physics of signal detection. That is, it becomes  
251 more difficult for a receiver to distinguish between the amplitudes of a weak signal that is also  
252 noisy than it does for a stronger signal that has the same amount of noise as the weaker signal.

253 An interesting finding was that the average CRI within each roughness rating category  
254 consistently increased in accordance with increasing overall route roughness. For example, the  
255 average CRI measured for the “rough” category increased by 64% from 0.140 for the smoother  
256 MW and UG segments to 0.230 for the rougher SG segment. That is, for the smoother routes,  
257 ratings of “rough” corresponded to much lower CRI values measured than for those of the  
258 roughest route. The pattern repeated for all the other rating categories, albeit the proportional  
259 increase was less. This result suggested that there was “roughness acclimation” such that the  
260 threshold of roughness perception increased as the route segments became rougher. The  
261 roughness acclimation phenomenon suggests that using the traveling public to obtain subjective  
262 assessments of ride quality could lead to non-uniform ratings and significant biases across  
263 different road segments.

## 264 **5 Conclusions**

265 The measurement of ride quality for the entire road network is an important but expensive

266 endeavor for transportation agencies in any nation. Over the years, methods to assess ride quality  
267 evolved from the subjective ratings of expert panels to their association with objective values  
268 derived from new measurement technologies. Both the subjective rating scales and the objective  
269 means of ride quality measurements varied and evolved over time. The emergence of connected  
270 vehicle technology presents a new opportunity to enact policies and standards for measuring the  
271 ride quality of all road networks, automatically and continuously. Hence, it is important to  
272 examine the relationship between such objective measures of ride quality and the levels of  
273 roughness perceived by the traveling public.

274         To emulate measurements from connected vehicles, this research used a smartphone on  
275 board buses to measure roughness from multidimensional motions and surveyed the riders to rate  
276 their ride quality into linguistic categories of roughness. The main policy considerations are that  
277 while the objective measurements of ride quality were distinguishable among different road  
278 segments, the corresponding subjective measurements were only distinguishable in the extremes  
279 of perceived roughness levels. That is, the traveling public was able to consistently distinguish  
280 between “very smooth” and “rough” rides but not rides with intermediate levels of roughness. In  
281 general, the ability of riders to distinguish among roughness categories becomes easier as the  
282 road segments become rougher.

283         Another important policy consideration is that roughness acclimation exists in ride  
284 quality ratings. That is, regular riders of a rough route appear to become acclimated to the ride  
285 quality and have an elevated threshold of roughness perception relative to riders of a smoother  
286 route. Hence, potential policies to replace expert panels with regular riders, perhaps by using  
287 app-based surveys, should consider this phenomenon because it can lead to non-uniform,  
288 inconsistent, and biased results. Policymakers need to be aware that using smartphones can result

289 in large variations in roughness measurements. Furthermore, measurements of roughness that  
290 utilize onboard inertial sensors account for perturbations due to driver behavior as well as road  
291 geometry and surface irregularities. Therefore, a limitation is that when the application is to  
292 isolate roughness due only to roadway anomalies, the analyst must separate the signals from each  
293 accelerometer direction, process them separately, and interpret them accordingly. Policies to  
294 enable connected vehicle measurements of ride quality should consider the standardization of  
295 sensor location, orientation, calibration, and sample rate to provide consistent ride quality  
296 evaluations. Future work will use the same method to compare the CRI of railroads with hi-rail  
297 personnel ratings to improve maintenance planning and decision making.

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